# **ERIC CHEN**

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### EDUCATION

Massachusetts Institute of Technology	
M. Eng., Electrical Engineering and Computer Science	2021
B.S., Physics	2020
B.S., Electrical Engineering and Computer Science	2020

#### PUBLICATIONS

Eric Chen\*, Zhang-Wei Hong\*, Joni Pajarinen, Pulkit Agrawal. Redeeming Intrinsic Rewards via Constrained Optimization, Conference on Neural Information Processing Systems (NeurIPS), 2022.

### EXPERIENCE

<b>Aurora Flight Sciences</b> AI/ML Research Engineer, <i>Dr. Sildomar Monteiro</i>	January 2022 – present
<ul> <li>Researching learning from demonstrations with Prof. Pulkit Agrawal (MIT); develocity develocity for the DARPA ShELL program</li> </ul>	veloping continual reinforcement learning
<ul> <li>PM and lead developer for S2A2 NASA ULI partnership</li> </ul>	
Improbable AI Group, MIT CSAIL Graduate Research Assistant, <i>Prof. Pulkit Agrawal</i>	September 2019 – January 2022
• Published a novel method that adaptively balances reward terms in reinforcement le	earning
MIT 6.832: Underactuated Robotics Graduate Teaching Assistant, Prof. Russ Tedrake	February 2021 – May 2021
Learning and Intelligent Systems Group, MIT CSAIL Undergraduate Researcher, <i>Prof. Leslie Kaelbling</i>	June 2019 – December 2019
<ul> <li>Improved efficiency of graph search algorithms by 25% by using lazy edge evalu methods (A*, LPA*, D* Lite), and profiling code in Julia</li> </ul>	ations; implemented simulation, baseline
<b>Little Devices Lab, MIT Edgerton</b> Undergraduate Researcher, <i>Jose Gomez-Marquez</i>	June 2019 – September 2019
<ul> <li>Prototyped a low-cost rapid disease testing platform (software/hardware); developed on the International Space Station</li> </ul>	software/hardware for a NASA experiment
Interactive Robotics Group, MIT CSAIL Undergraduate Researcher, <i>Prof. Julie Shah</i>	September 2018 – June 2019
• Implemented safe simulation to real-world transfer of a learned control policy on a	robot car using ROS
<b>Rev.com</b> Software Engineering Intern	June 2018 – August 2018
• Collaborated within a 5-person team to deploy production-ready features for autom	nated speech-to-text transcription services
Marine Robotics Group, MIT CSAIL Undergraduate Researcher, <i>Prof. John Leonard</i>	January 2018 – May 2018
• Designed and integrated visual-based obstacle avoidance on the Remote Explorer (	REx) autonomous marine vehicle
HONORS AND AWARDS	

National Science Foundation Graduate Research Fellowship Program (NSF GRFP), honorable mention	2021
Amazon Web Services Machine Learning Research Awards (AWS MLRA) Grant, \$100,000	2020
MIT Emerson Music Scholar	2016 - 2018

#### SKILLS

Skills	Python, C++, ROS, PyTorch, Tensorflow, Docker, AWS/GCP, Git, Bash, Julia, C $\#$
Selected courses	Statistical Learning Theory, Computational Sensorimotor Learning
	Computer Vision, Embodied Intelligence, Underactuated Robotics, Robotics Science and Systems